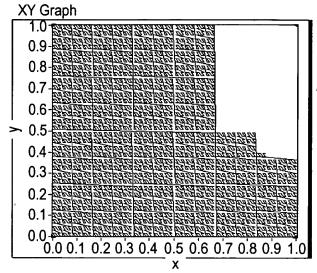
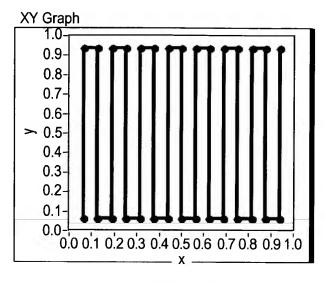
DIPE CITY



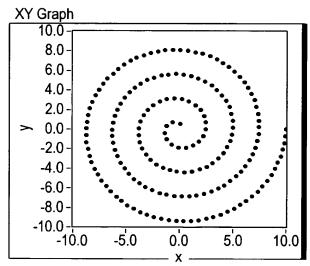
Approximated Peano Curve. The space-filling process has not been completed.

Figure 1A (Prior Art)



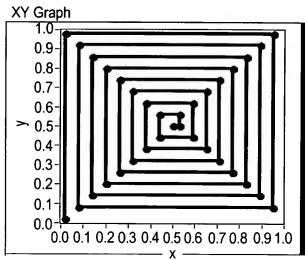
Boustrophedon Path

Figure 1B (Prior Art)



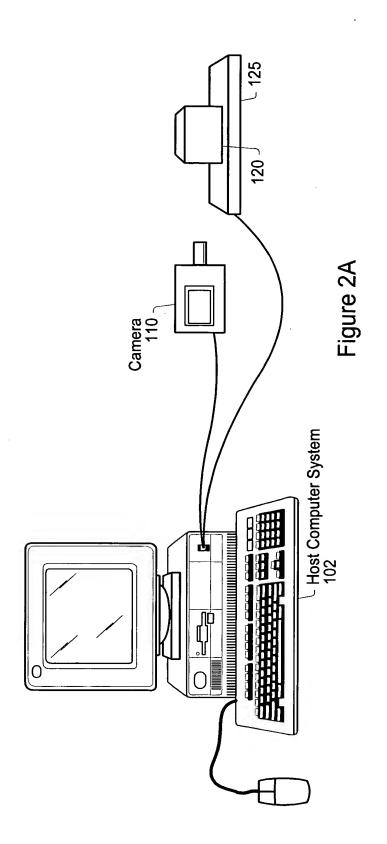
Archimedes Spiral defined by equally distributed points

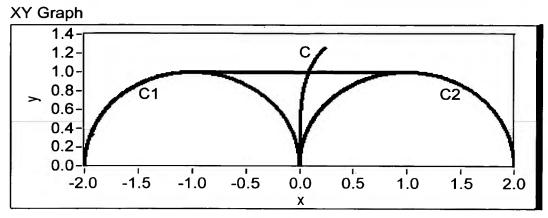
Figure 1C (Prior Art)



Spiral-like line-based scanning

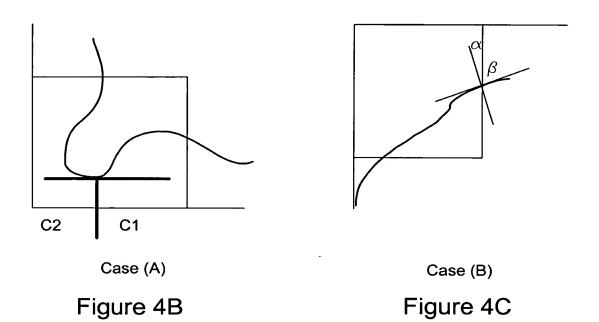
Figure 1D (Prior Art)

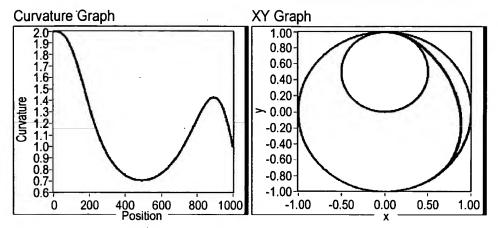




The situation of Lemma 1

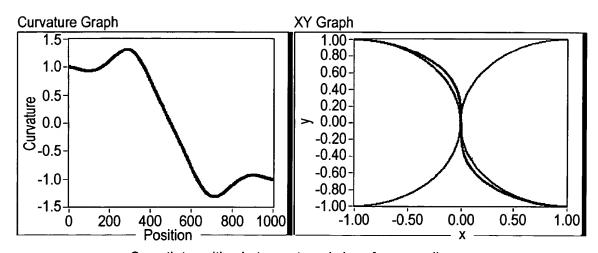
Figure 4A





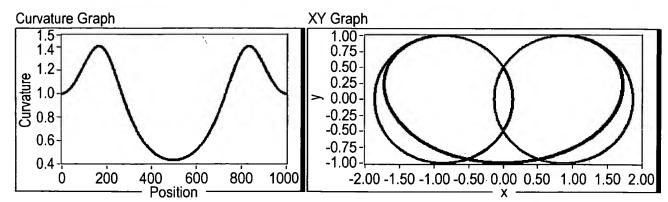
Smooth transition between two circles of different radii.

Figure 4D



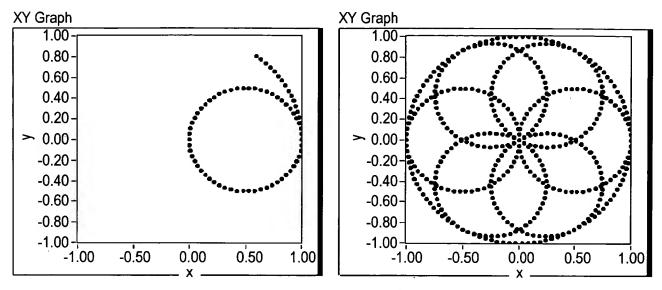
Smooth transition between two circles of same radius.

Figure 4E



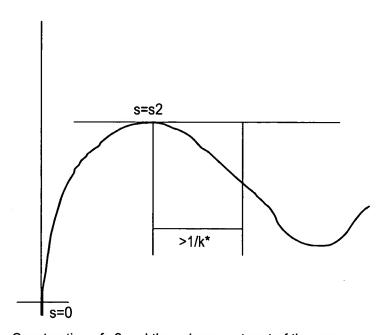
Transition between two unit circles of radius 1. The distance between the circles is sqrt(3)

Figure 4F



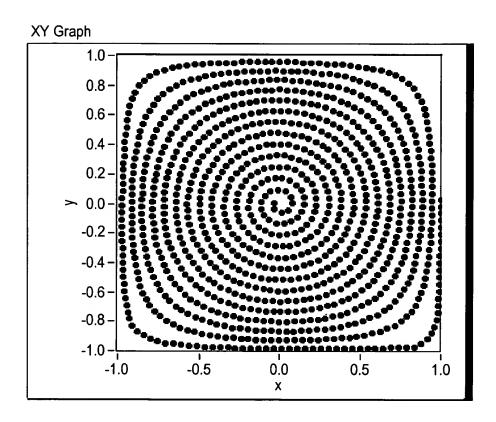
Beginning (left) and completion (right) of a scanning scheme where the curvature is below a certain value

Figure 5A



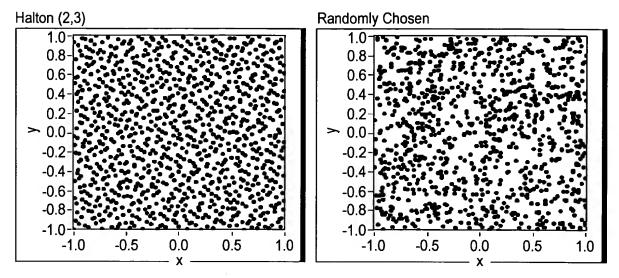
Construction of s2 and the subsequent part of the curve

Figure 5B



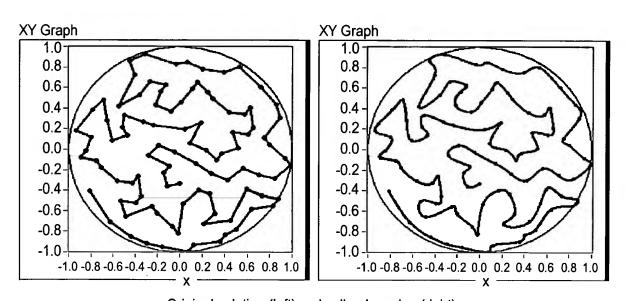
Conformal Spiral.

Figure 6



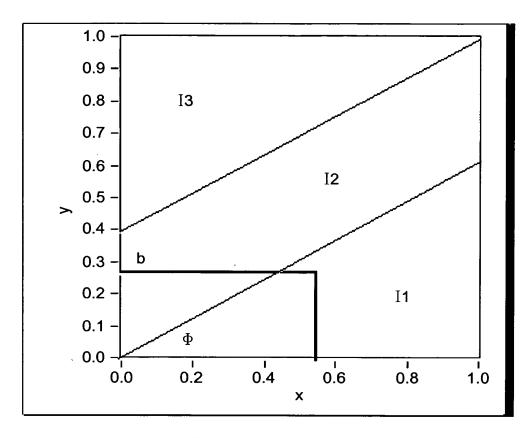
The first 1000 Halton points (left) and randomly chosen points (right)

Figure 8A



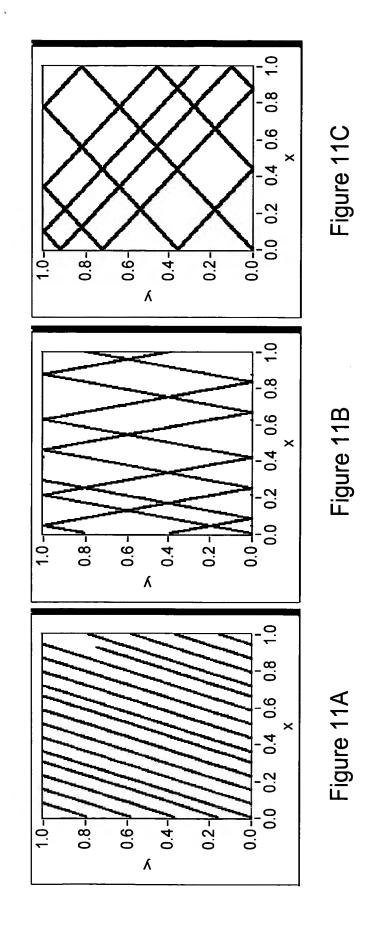
Original solution (left) and splined version (right).

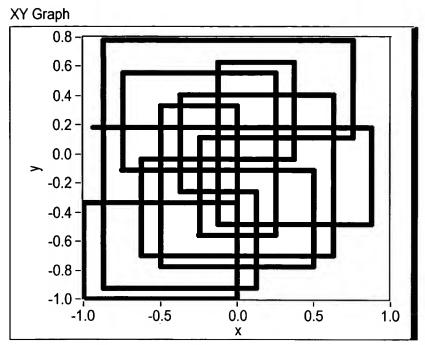
Figure 8B



Definition of I_1 , I_2 , and I_3

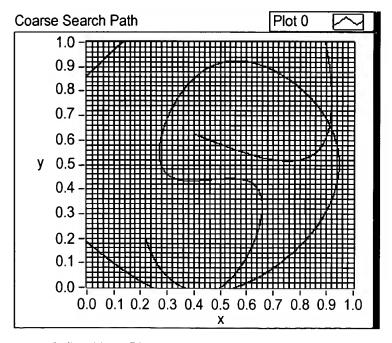
Figure 10





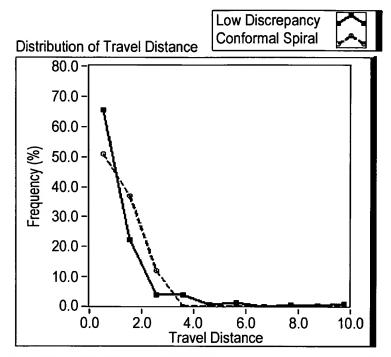
Beginning of a Low Discrepancy Curve based on a specific Halton Sequency in 2d

Figure 13A



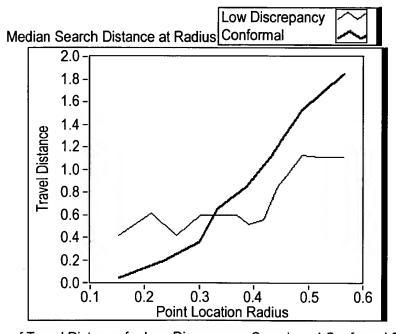
Splined Low Discrepancy Curve coarse search

Figure 13B



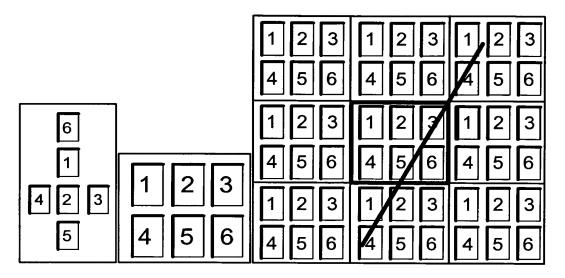
Comparison of Conformal Spiral and Low Discrepancy Searching

Figure 13C



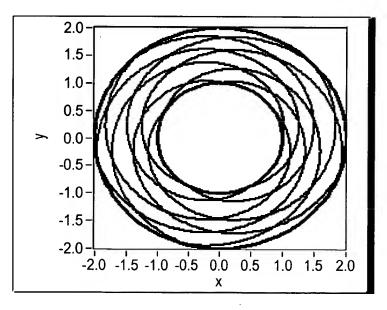
Comparison of Travel Distance for Low Discrepancy Search and Conformal Spiral Search

Figure 13D



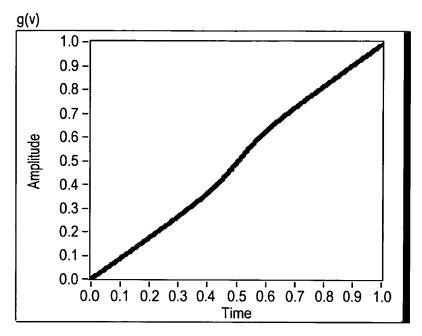
Tiling of the plane and relation to the surface of the unit cube

Figure 15A



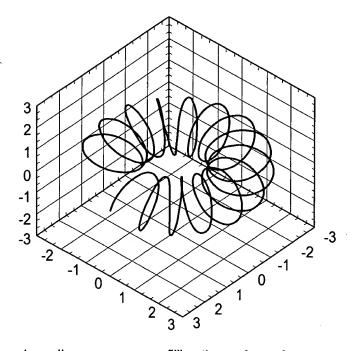
Low-discrepancy curve in a ring

Figure 15B



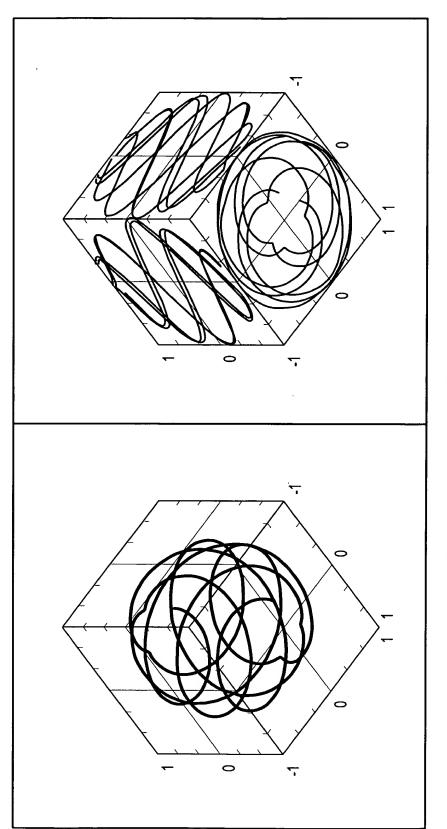
Low Discrepancy Preserving Mapping Function

Figure 15C



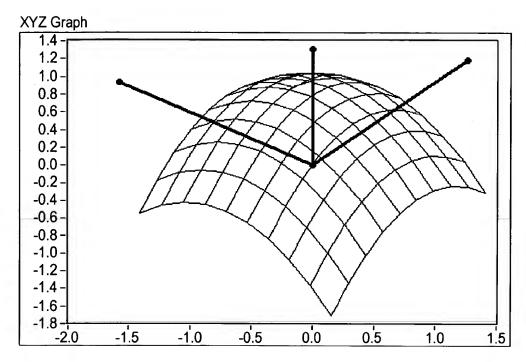
Low-discrepancy curve filling the surface of a torus

Figure 15D



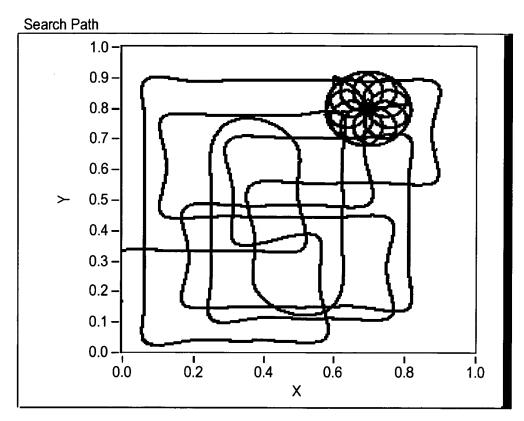
Low-discrepancy curve on a sphere (left) and projections (right)

Figure 16



Surfaces can be scanned efficiently when the term low discrepancy sequence/ curve can be generalized, e.g. based on metrics on the surface.

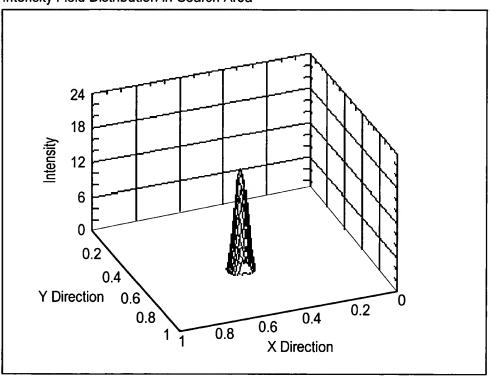
Figure 18



Splined Low Discrepancy Curve coarse search with refined final approach

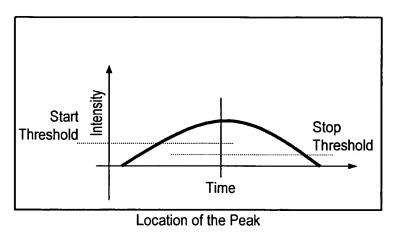
Figure 19

Intensity Field Distribution in Search Area



Beam intensity distribution in search area

Figure 20



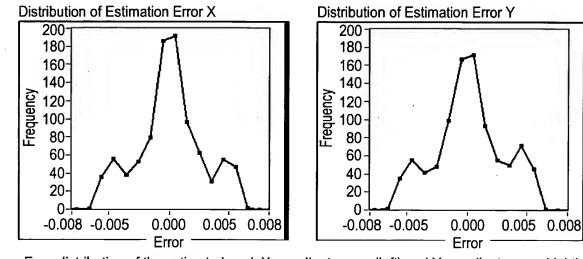
Peak Estimate

Spot

Initial Final Approach Move

Figure 21A

Figure 21B



Error distribution of the estimated peak X coordinate error (left) and Y coordinate error (right)

Figure 21C